# **Analytical Mechanics**

# Exercises 1.17-1.24

(Exercise descriptions [with possible slight modifications] from Analytical Mechanics by Fowles and Cassiday, 7th International Student Edition. Solutions by: Waves and Tensors) **Exercise 1.17:** A small ball is fastened to a long rubber band and twirled around in such a way that the ball moves in an elliptical path given by the equation

 $\mathbf{r}(t) = \mathbf{i}b\cos(\omega t) + \mathbf{j}2b\sin(\omega t),$ 

where b and  $\omega$  are constants. Find the speed of the ball as a function of t. In particular, find v at t = 0 and  $t = \frac{\pi}{2\omega}$ , at which times the ball is, respectively, at its minimum and maximum distances from the origin.

#### Solution:

We get the velocity of the ball from equation (1.10.3):  $\mathbf{v} = \frac{d\mathbf{r}}{dt} = -\mathbf{i}b\omega\sin(\omega t) + \mathbf{j}2b\omega\cos(\omega t).$ The speed is thus:

$$v = |\mathbf{v}| = [(-b\omega\sin(\omega t))^2 + (2b\omega\cos(\omega t))^2]^{\frac{1}{2}}$$
  
=  $[b^2\omega^2\sin^2(\omega t) + 4b^2\omega^2\cos^2(\omega t)]^{\frac{1}{2}}$   
=  $|b| \cdot |\omega| \cdot [\sin^2(\omega t) + 4\cos^2(\omega t)]^{\frac{1}{2}}.$ 

At t = 0 we have  $v = |b||\omega| \cdot [\sin^2 0 + 4\cos^2 0]^{\frac{1}{2}} = 2|b||\omega|$ . At  $t = \frac{\pi}{2\omega}$  we have  $v = |b||\omega| \cdot [\sin^2 \frac{\pi}{2} + 4\cos^2 \frac{\pi}{2}]^{\frac{1}{2}} = |b||\omega|$ . **Exercise 1.18:** A buzzing fly moves in a helical path given by the equation  $\mathbf{r}(t) = \mathbf{i}b\sin(\omega t) + \mathbf{j}b\cos(\omega t) + \mathbf{k}ct^2.$ 

Show that the magnitude of the acceleration of the fly is constant, provided  $b,\omega$  and c are constant.

## Solution:

The acceleration of the fly we get from equation (1.10.8):

$$\mathbf{a} = \frac{d^2 \mathbf{r}}{dt^2} = -\mathbf{i}b\omega^2 \sin(\omega t) - \mathbf{j}b\omega^2 \cos(\omega t) + \mathbf{k}2c.$$

The magnitude of the acceleration is:

$$\begin{aligned} |\mathbf{a}| &= [(-b\omega^2 \sin(\omega t))^2 + (-b\omega^2 \cos(\omega t))^2 + (2c)^2]^{\frac{1}{2}} \\ &= [b^2 \omega^4 \sin^2(\omega t) + b^2 \omega^4 \cos^2(\omega t) + 4c^2]^{\frac{1}{2}} \\ &= [b^2 \omega^4 + 4c^2]^{\frac{1}{2}} \\ &= \text{constant.} \end{aligned}$$

**Exercise 1.19:** A bee goes out from its hive in a spiral path given in plane polar coordinates by

$$r = be^{kt}, \ \theta = ct,$$

where b, k, and c are positive constants. Show that the angle between the velocity vector and the acceleration vector remains constant as the bee moves outward. (*Hint: Find*  $\frac{\mathbf{v} \cdot \mathbf{a}}{va}$ .)

#### Solution:

We get  $r = be^{kt}$ ,  $\dot{r} = bke^{kt}$ ,  $\ddot{r} = bk^2e^{kt}$ ,  $\theta = ct$ ,  $\dot{\theta} = c$  and  $\ddot{\theta} = 0$ . Plugging these values into equations (1.11.7) and (1.11.9) we get:

$$\mathbf{v} = bke^{kt}\mathbf{e}_r + bce^{kt}\mathbf{e}_{\theta}$$
$$\mathbf{a} = (bk^2e^{kt} - be^{kt} \cdot c^2)\mathbf{e}_r + (be^{kt} \cdot 0 + 2bke^{kt} \cdot c)\mathbf{e}_{\theta} = (k^2 - c^2)be^{kt}\mathbf{e}_r + 2bcke^{kt}\mathbf{e}_{\theta}$$
We get the cosine of the angle  $\phi$  between **a** and **v** from equation (1.4.6):

We get the cosine of the angle  $\phi$  between **a** and **v** from equation (1.4.6):

$$\begin{split} \cos \phi &= \frac{\mathbf{v} \cdot \mathbf{a}}{va} \;\; = \;\; \frac{bke^{kt} \cdot (k^2 - c^2)be^{kt} + bce^{kt} \cdot 2bcke^{kt}}{[(bke^{kt})^2 + (bce^{kt})^2]^{\frac{1}{2}} \cdot [((k^2 - c^2)be^{kt})^2 + (2bcke^{kt})^2]^{\frac{1}{2}}} \\ &= \; \frac{(k^2 - c^2)b^2k + 2b^2c^2k}{[b^2k^2 + b^2c^2]^{\frac{1}{2}} \cdot [(k^2 - c^2)^2b^2 + 4b^2c^2k^2]^{\frac{1}{2}}} \\ &= \; \frac{(k^2 - c^2)k + 2c^2k}{[k^2 + c^2]^{\frac{1}{2}} \cdot [(k^2 - c^2)^2 + 4c^2k^2]^{\frac{1}{2}}} \\ &= \; \frac{(k^2 + c^2)k}{(k^2 + c^2)^{\frac{1}{2}} \cdot [(k^2 + c^2)^2]^{\frac{1}{2}}} \\ &= \; \frac{k}{\sqrt{k^2 + c^2}} \\ &= \; \text{constant.} \end{split}$$

**Exercise 1.20:** Work Exercise 1.18 using cylindrical coordinates where  $R = b, \phi = \omega t$ , and  $z = ct^2$ .

### Solution:

We get  $R = b, \dot{R} = 0, \ddot{R} = 0, \phi = \omega t, \dot{\phi} = \omega, \ddot{\phi} = 0, z = ct^2, \dot{z} = 2ct$  and  $\ddot{z} = 2c$ . We get the acceleration of the fly from equation (1.12.3):  $\mathbf{a} = (0 - b \cdot \omega^2)\mathbf{e}_R + (2 \cdot 0 \cdot \omega + b \cdot 0)\mathbf{e}_{\phi} + 2c\mathbf{e}_z = -b\omega^2\mathbf{e}_R + 2c\mathbf{e}_z$ The magnitude of the acceleration of the fly is thus:  $|\mathbf{a}| = [(-b\omega^2)^2 + (2c)^2]^{\frac{1}{2}} = [b^2\omega^4 + 4c^2]^{\frac{1}{2}},$ which is the same result as in Exercise 1.18. **Exercise 1.21:** The position of a particle as a function of time is given by  $\mathbf{r}(t) = \mathbf{i}(1 - e^{-kt}) + \mathbf{j}e^{kt}$ ,

where k is a positive constant. Find the velocity and acceleration of the particle. Sketch its trajectory.

### Solution:



$$\mathbf{v}(t) = \frac{d\mathbf{r}(t)}{dt} = ke^{-kt}\mathbf{i} + ke^{kt}\mathbf{j}$$
$$\mathbf{a}(t) = \frac{d\mathbf{v}(t)}{dt} = -k^2e^{-kt}\mathbf{i} + k^2e^{kt}\mathbf{j}$$
$$\mathbf{r}(0) = \mathbf{j} \text{ and } \mathbf{r}(t \to \infty) = \mathbf{i} + \infty \cdot \mathbf{j}.$$

**Exercise 1.22:** An ant crawls on the surface of a ball of radius b in such a manner that the ant's motion is given in spherical coordinates by the equations

 $r = b, \ \phi = \omega t, \ \theta = \frac{\pi}{2} [1 + \frac{1}{4} \cos(4\omega t)].$ 

Find the speed of the ant as a function of the time t. What sort of path is represented by the above equations?



Solution:

We get  $r = b, \dot{r} = 0, \phi = \omega t, \dot{\phi} = \omega, \theta = \frac{\pi}{2} [1 + \frac{1}{4} \cos(4\omega t)], \dot{\theta} = -\frac{\pi}{2} \omega \sin(4\omega t).$ We get the velocity of the ant from equation (1.12.12):  $\mathbf{v}(t) = b\omega \sin(\frac{\pi}{2} [1 + \frac{1}{4} \cos(4\omega t)]) \mathbf{e}_{\phi} - \frac{\pi}{2} b\omega \sin(4\omega t) \mathbf{e}_{\theta}.$ 

So the speed of the ant is:

$$\begin{aligned} |\mathbf{v}(t)| &= [b^2 \omega^2 \sin^2(\frac{\pi}{2} [1 + \frac{1}{4} \cos(4\omega t)]) + \frac{\pi^2}{4} b^2 \omega^2 \sin^2(4\omega t)]^{\frac{1}{2}} \\ &= b|\omega| [\sin^2(\frac{\pi}{2} [1 + \frac{1}{4} \cos(4\omega t)]) + \frac{\pi^2}{4} \sin^2(4\omega t)]^{\frac{1}{2}}. \end{aligned}$$

At t = 0:  $r = b, \phi = 0$  and  $\theta = \frac{\pi}{2}(1 + \frac{1}{4}) = \frac{5\pi}{8}$ .

r does not change so the ant is always on the surface of the ball.  $\phi$  increases (assuming  $\omega > 0$ ) linearly with time t whereas  $\theta$  changes between a minimum of  $\frac{\pi}{2}(1-\frac{1}{4}) = \frac{3\pi}{8}$  and a maximum of  $\frac{5\pi}{8}$ .  $\theta$  changes periodically in a cosinesoidal way.

**Exercise 1.23:** Prove that  $\mathbf{v} \cdot \mathbf{a} = v\dot{v}$  and, hence, that for a moving particle  $\mathbf{v}$  and  $\mathbf{a}$  are perpendicular to each other if the speed v is constant. (*Hint: Differentiate both sides of the equation*  $\mathbf{v} \cdot \mathbf{v} = v^2$  with respect to t. Note,  $\dot{v}$  is not the same as  $|\mathbf{a}|$ . It is the magnitude of the acceleration of the particle along its instantaneous direction of motion.)

#### Solution:

From equation (1.9.5) we get:  $v^2 = \mathbf{v} \cdot \mathbf{v} \Rightarrow 2v\dot{v} = \frac{d\mathbf{v}}{dt} \cdot \mathbf{v} + \mathbf{v} \cdot \frac{d\mathbf{v}}{dt} \Rightarrow \mathbf{v} \cdot \mathbf{a} = v\dot{v}.$ If  $v = \text{constant then } \dot{v} = 0 \text{ and } \mathbf{v} \cdot \mathbf{a} = 0 \text{ so } \mathbf{v} \text{ and } \mathbf{a} \text{ are perpendicular.}$  Exercise 1.24: Prove that

 $\frac{d}{dt}[\mathbf{r}\cdot(\mathbf{v}\times\mathbf{a})]=\mathbf{r}\cdot(\mathbf{v}\times\dot{\mathbf{a}}).$ 

# Solution:

We get from equations (1.9.5) and (1.9.6):

$$\frac{d}{dt}[\mathbf{r} \cdot (\mathbf{v} \times \mathbf{a})] = \frac{d\mathbf{r}}{dt} \cdot (\mathbf{v} \times \mathbf{a}) + \mathbf{r} \cdot \frac{d}{dt}(\mathbf{v} \times \mathbf{a})$$
$$= \mathbf{v} \cdot (\mathbf{v} \times \mathbf{a}) + \mathbf{r} \cdot (\frac{d\mathbf{v}}{dt} \times \mathbf{a} + \mathbf{v} \times \frac{d\mathbf{a}}{dt})$$
$$= 0 + \mathbf{r} \cdot (0 + \mathbf{v} \times \dot{\mathbf{a}})$$
$$= \mathbf{r} \cdot (\mathbf{v} \times \dot{\mathbf{a}}).$$